

|   |  |  |
|---|--|--|
|  | <b>MPB S.r.l.</b><br>Via Giacomo Peroni 400/402<br>00131 ROMA (RM) | Tel +39 0641200744<br>Fax +39 0641200653<br>info@gruppompb.com |
|   |  | <a href="http://www.gruppompb.com">www.gruppompb.com</a>       |

User's manual

# **SEMS**

Shielding effectiveness measurement  
system

## **SAFETY NOTE**

Read before using the product

MPB works to provide to its customers the best safety conditions available complying with the current safety standards.

The instrumentation described in this manual has been produced, tested and left the factory in conditions that fully complying the European standards.

To maintain it in safe conditions and ensure the correct use, these general instructions must be fully understood and applied before using the product.

This product is designed for industrial environment and laboratories and should be used by skilled staff only.

MPB disclaims responsibility for a different use of the device.

## Conformity Certificate



(in accordance with the Directives: EMC 89/336/EEC and Low Voltage 73/23/EEC)

This is to certify that the product: SEMS  
(Measurement system of shielding effectiveness)

complies with the following European Standards:

Safety: CEI EN 61010-1 (2001)

EMC: EN 61326-1 (2007)

This product complies with the requirements of the Low Voltage Directive  
2006/95/CE, and with the EMC Directive 2004/108/CE.

MPB S.r.l.

## Index

|   |             |
|---|-------------|
| <b>1. General information</b>                                     | <b>Pag.</b> |
| 1.1. Introduction   | 5           |
| 1.2. System description   | 5           |
| 1.3. Standard accessories   | 6           |
| 1.4. Optional accessories   | 6           |
| 1.5. Receiver front panel   | 7           |
| 1.6. Transmitter front panel                                      | 7           |
| 1.7. Receiver/transmitter rear panel                              | 8           |
| 1.8. Technical specifications                                     | 9           |
| <b>2. Operating principle</b>                                     |             |
| 2.1. SEMS receiver  | 10          |
| 2.2. SEMS transmitter   | 10          |
| 2.3. SEMS system  | 11          |
| <b>3. System use and operation</b>                                |             |
| 3.1. Std Menu   | 12          |
| 3.1.1. Cal Menu   | 13          |
| 3.1.2. Show Menu  | 15          |
| 3.1.3. Meas Menu  | 17          |
| 3.2. WIZ Menu   | 19          |
| 3.2.1. Measurements using wizard                                  | 20          |
| 3.3. Menu Spt   | 24          |
| 3.4. Measuring the shielding attenuation                          | 25          |
| 3.5. Calibration using CalKit                                     | 26          |
| 3.6. How to use the active bridge                                 | 28          |
| 3.7. Measurement with Rod antennas mod. R1                        | 29          |
| <b>4. <u>SEMS PC Utility</u> software, controls and functions</b> |             |
| 4.1. Installation   | 30          |
| 4.2. Archive Mode   | 31          |
| 4.3. List Mode  | 32          |
| 4.4. Receiver firmware upgrading                                  | 33          |

# 1. General information

## 1.1. Introduction

SEMS is thought to comply the raising need to test and verify the shielding effectiveness of shielded environment in hospitals and industries.

This system allows to measure automatically with high speed and accuracy the attenuation value of the magnetic and electric field in shielded environments.

## 1.2. System description

The shielding effectiveness measurement system has a transmitter and a receiver, both of them are provided with a pair of very small antennas, one is used to measure the magnetic field attenuation in the 2MHz to 128MHz frequency range, the other one is used to measure the electric field attenuation in the 60 to 300MHz frequency range.

Contrary to today's available systems, that measures the shield effectiveness on few frequency points, SEMS allows to perform a complete test on the whole frequency ranges continuously. Another improvement compared to the standard system is the component synchronization, TX and RX are connected by a wireless system that allows to perform automatically the measurement minimizing the user's errors.

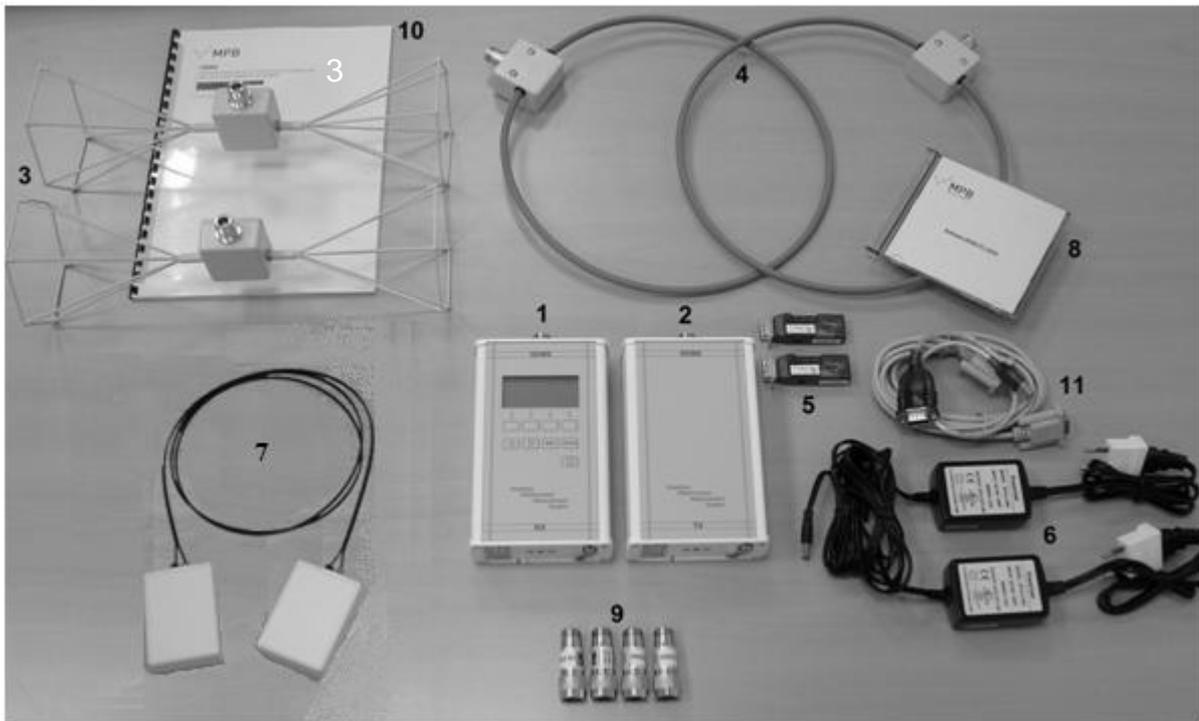


Picture n°01

SEMS in the transport bag

### 1.3. Standard accessories

- 1) SEMS receiver
- 2) SEMS transmitter
- 3) 2 biconical antennas (60...300 MHz)
- 4) 2 loop antennas (2...128 MHz)
- 5) 2 RS232/wireless
- 6) 2 Battery chargers
- 7) Active bridge at 2.4GHz
- 8) PC Utility SEMS software
- 9) Cal Kit and SIT calibration certificate
- 10) User's Manual
- 11) RS232 cable and RS232-USB adapter
- 12) Instrumentation case



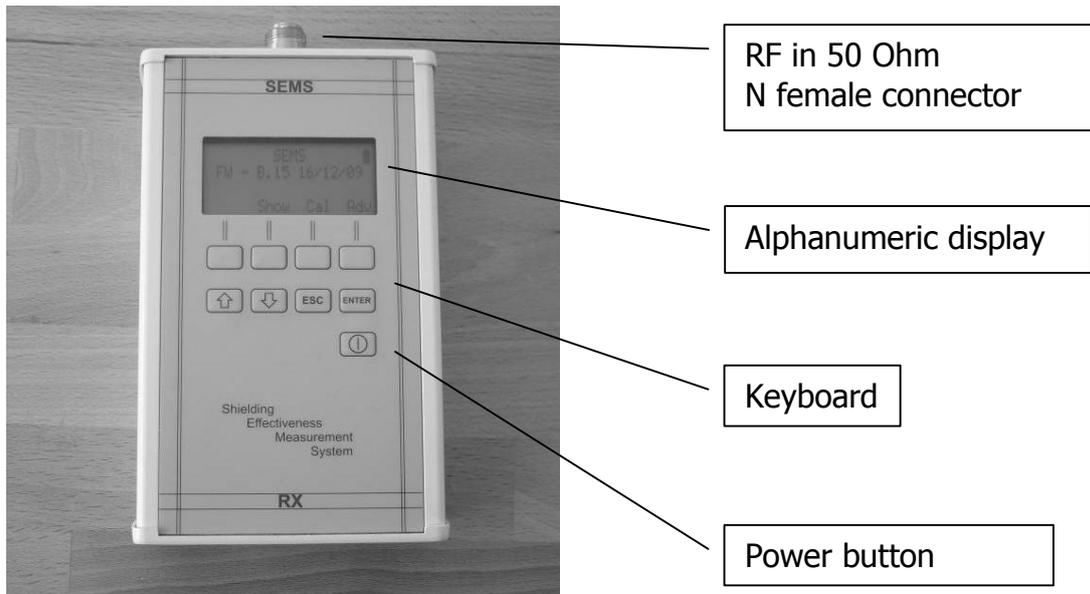
Picture n°02

### 1.4. Optional accessories

- 2 Loop antennas Mod. L2, 10 kHz...4 MHz frequency range
- 2 Rod antennas Mod. R1, 1MHz...60 MHz frequency range (read chapter 3.7)
- 2 Wooden tripod Mod. TR-02-A

### 1.5. Receiver front panel

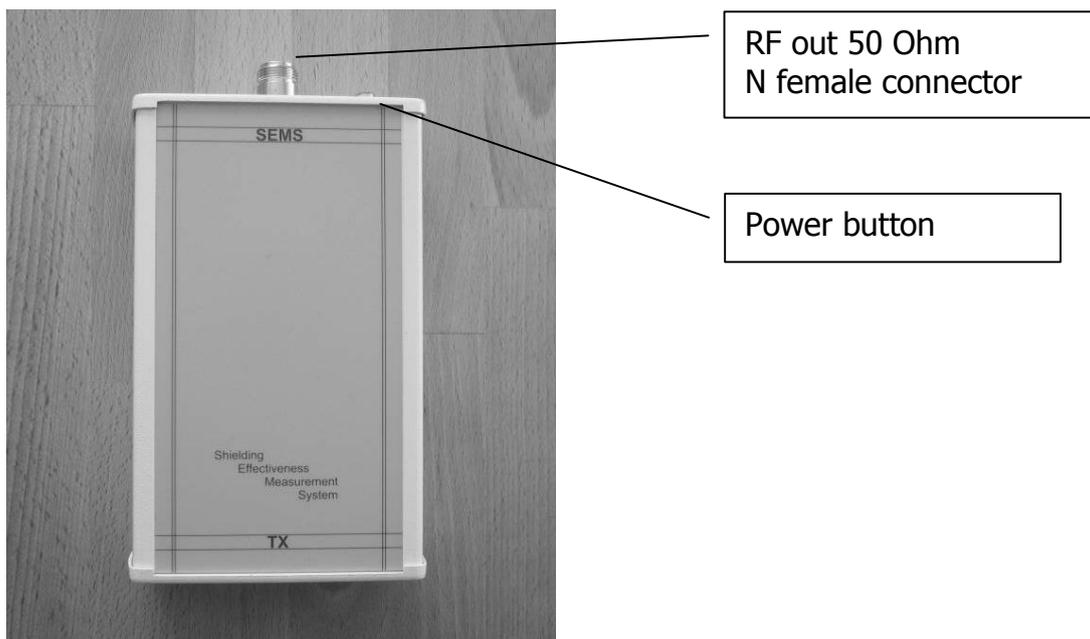
In the Picture below(n°03) is represented SEMS receiver front panel. It has a display and a command keyboard.



Picture n°03

### 1.6. Transmitter front panel

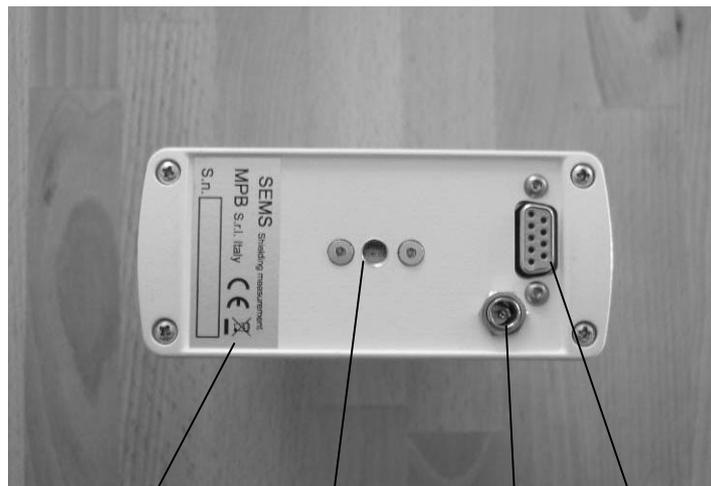
The SEMS transmitter (Picture n° 04) has no command button but a power button, since the commands are sent by the receiver using the wireless connection.



Picture n°04

## 1.7. Receiver / Transmitter rear panel

The rear panels (Picture n° 05) are equals for both devices and upon them is possible to find the serial number, the thread used for the tripod, the battery charger connector and the RS232 interface for the wireless link.



Picture n°05

Serial  
number

Thread insert ¼

Battery charger  
connector

RS232

**Important note:** Always use the battery charger provided with the instrument to avoid serious damages to the devices and operator's injuries.

**Important note:** The battery charger must be connected with both devices (Tx and Rx) turned off.

## 1.8. Technical specifications

| <b>SEMS</b>  |   |
|--|---|
| <b>Frequency range for TX/RX</b>                     | 10 kHz...300 MHz  |
| Resolution   | 10 Hz   |
| <b>RF out</b> (TX module)                            | $Z_{out}$ 50 $\Omega$ , N fem.                                |
| Max output power (typical)                           | +30 dBm   |
| <b>RF in</b> (RX module)                             | $Z_{in}$ 50 $\Omega$ , N fem.                                 |
| VSWR   | < 1.2   |
| Attenuator   | 0...20dB  |
| Max input power                                      | 110 dBuV  |
| <b>IF bandwidth</b> (RX module)                      |   |
| 3 dB bandwidth                                       | 5/150Hz   |
| <b>Attenuation measurement accuracy</b><br>(typical) | 10 kHz...30 MHz $\pm$ 1.0 dB<br>30 MHz...300 MHz $\pm$ 1.5 dB |
| <b>I/O interface</b>                                 | RS232 / Wireless  |
| <b>Buzzer</b>  | To set on attenuation level                                   |
| <b>International standard compliancy</b>             | MIL-Std-285 IEEE Std 299 EN 50147-1<br>NSA65-6                |
| <b>Operating temperature</b>                         | 0°...40°C   |
| <b>Battery</b>                                       | Irreplaceable and rechargeable Li-Ion<br>(6 h operating time) |
| <b>Antennas</b>                                      |   |
| Loop Mod.L1  | Frequency range 2...128 MHz<br>Diameter 30 cm                 |
| Biconical Mod. B1                                    | Frequency range 60...300 MHz<br>Width 35 cm                   |
| <b>Calibration Set-Up and Measurement</b>            | Programmable by software                                      |
| <b>Options</b>                                       |   |
| Loop Antennas Mod.L2                                 | Frequency range 10kHz...4 MHz<br>Diameter 30 cm               |
| Rod Antennas Mod. R1                                 | Frequency range 1 MHz...60 MHz                                |
| Wooden tripod Mod. TR-02-A                           | Height settable   |
| Optic link 30 m                                      |   |
| <b>Weight and dimensions</b>                         |   |
| Overall weight                                       | 9,4 kg  |
| Case dimensions                                      | 52x43x23cm  |

Technical specifications may change without notice

## 2. Operating principle

### 2.1. SEMS Receiver

The block diagram (a) below represents the SEMS receiver.

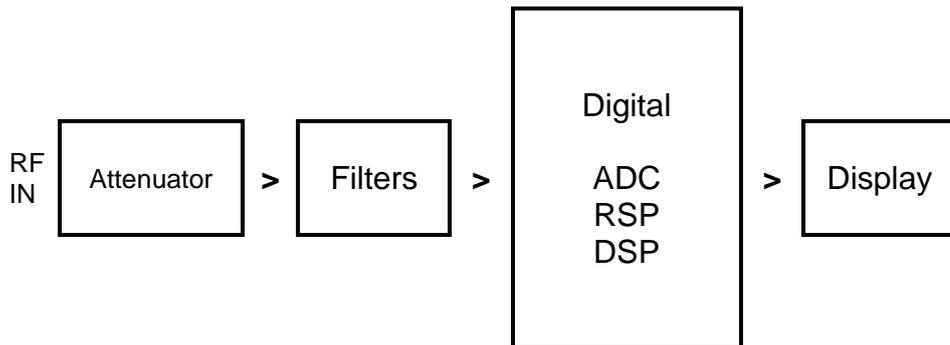


Figure a)

First of all the RF signal received by the antenna is attenuated by the attenuator module to fit the level to the next modules specifications, subsequently we can find the filters to select the bandwidth depending on the frequency settings. Then the RF signal is converted by an ADC and is processed by the digital part with a RSP and a DSP, the result will be shown on the display.

### 2.2. SEMS Transmitter

The block diagram below (b) represents the SEMS transmitter.

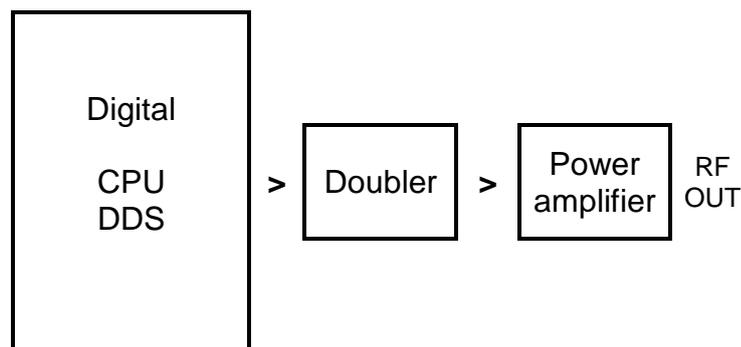


Figure b)

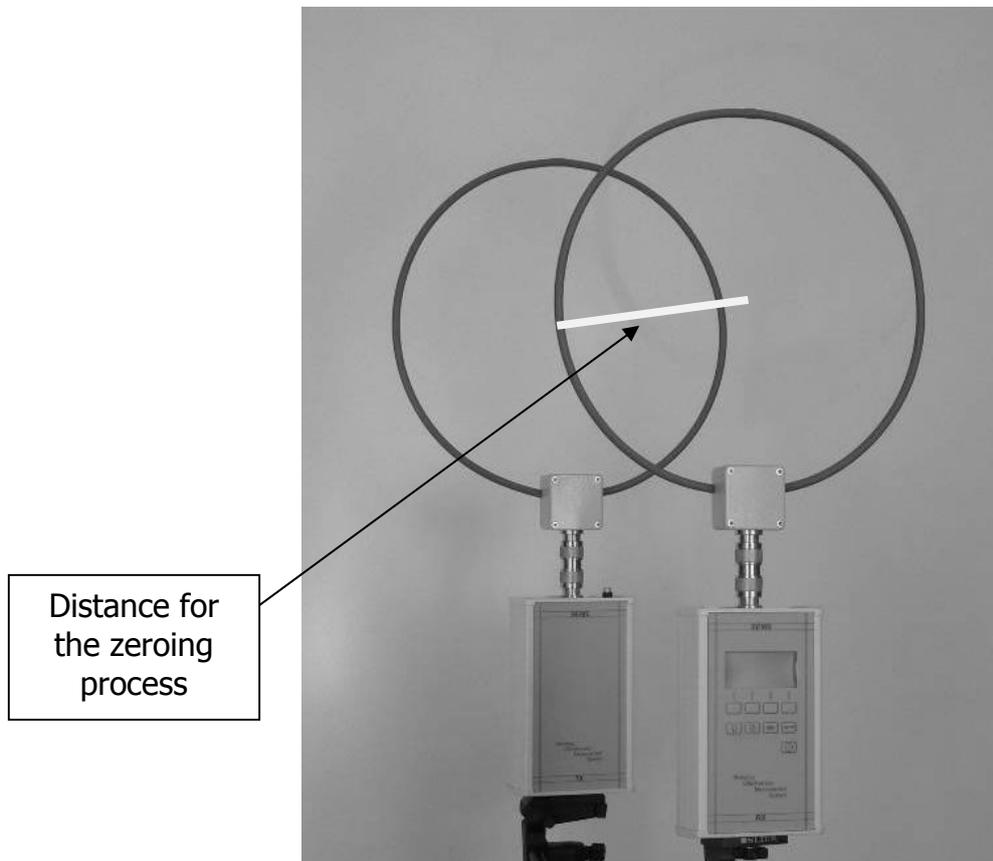
The transmitting signal is generated using the DDS controlled by the CPU that receives the instructions from the receiver wireless interface, this signal is duplicated and amplified in order to achieve the necessary level to be transmitted by the transmitting antenna.

### 2.3. SEMS System

The main purpose of the SEMS is to measure the shielding effectiveness in a shielded environment by measuring the attenuation of the electric or magnetic field.

We can briefly describe the operating principle as it follows:

The transmitter generate a RF signal and irradiates it through the antenna, at a certain distance the receiver catches the signal with an equal antenna and measures the signal level. If we move the receiver inside the shielded environment maintaining the same distance from the transmitter we will get a lower signal, so we can consider the shielding attenuation the difference between the reduced and the original signal.



Picture n°06

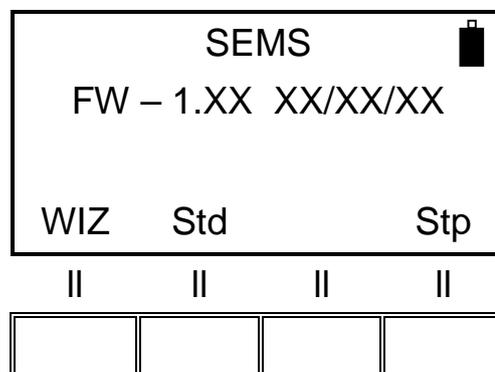
Example of zeroing with loop antennas

## 3. System use and operations

### Turn on menu

By pressing the power button of the RX module the device will turn on, to turn it off press the power button for at least 4 seconds. Follow the same procedure for the TX module.

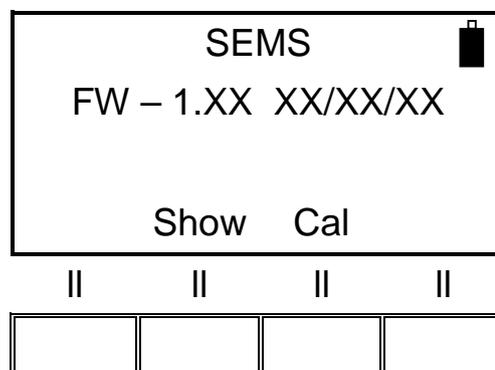
As soon as the device is turned on, the display will show the following screenshot. On the top right of the screen will appear a battery icon to show the charge status of the RX module, after the TX connection on the top left will appear the TX device battery icon.



**NOTE:** As soon as the connection is established, if the red led of the wireless devices blink together with the yellow ones, wait until the complete switching off of the first ones in order to let the devices synchronize and ensure the correct functioning.

### 3.1 Std Menu

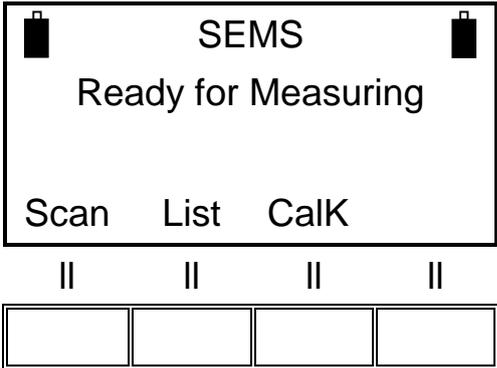
By pressing the Std menu button this screenshot will appear



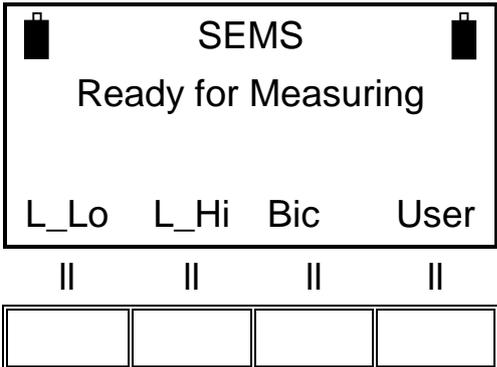
Then pressing the relative button allows the access to **Show** and **Cal** menu.

### 3.1.1. Cal Menu

**Cal** menu is used to perform the system zeroing process(Scan or List) or the system calibration process(CalK)

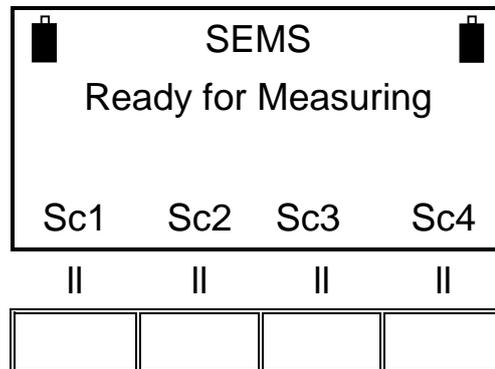


**Scan** performs the system zeroing process using the standard or customized frequency bands, by pressing the scan button we will see the following screenshot where is possible to choose the default bands (**L\_Lo**, **L\_Hi** e **Bic**) or the user's customized bands pressing the **User** button (customized bands are programmed with the "SEMS PC\_Utility" software)

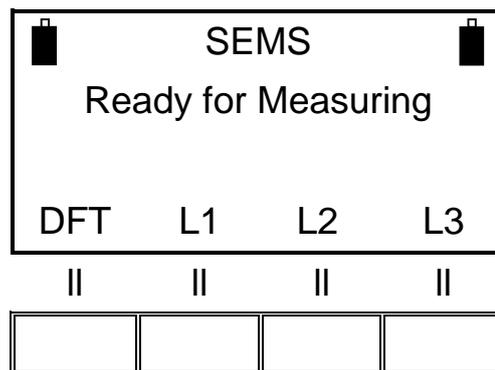


The choice of the button to press depends on the different types of antennas:  
**L\_Lo** (Loop antennas Mod. L2)  
**L\_Hi** ( Loop antennas Mod. L1)  
**Bic** (Biconical antennas Mod. B1)

Pressing **User** button will appear this screenshot to choose the memorized band:



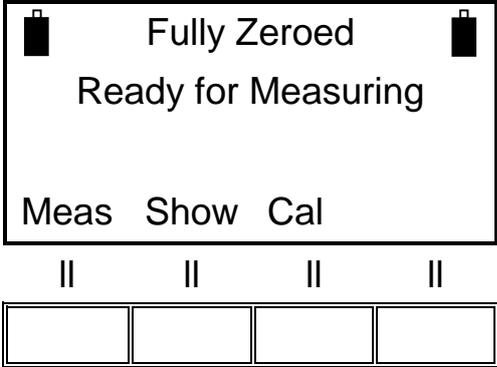
**List** performs the system zeroing process using the default or programmable frequency list, by pressing list button will appear a new menu where you can select the default frequency list **DFT** or three programmable lists (**L1**, **L2** e **L3**)



**CalK** performs the system calibration process using the four 30 dB attenuators supplied in the CAL-KIT.

NOTE: This procedure needs a wireless connection between TX and RX, you can control the connection with the battery status on the left top of the screen of RX (will be visible only if the connection has been successful).

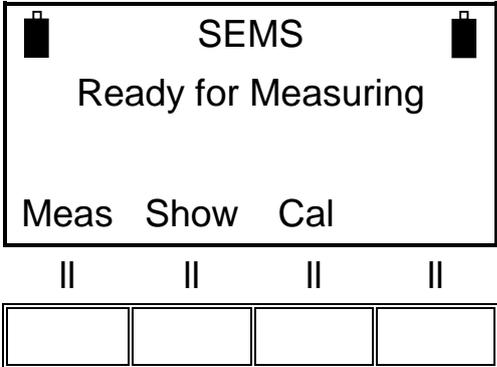
When the zeroing procedure ends the following menu will appear:



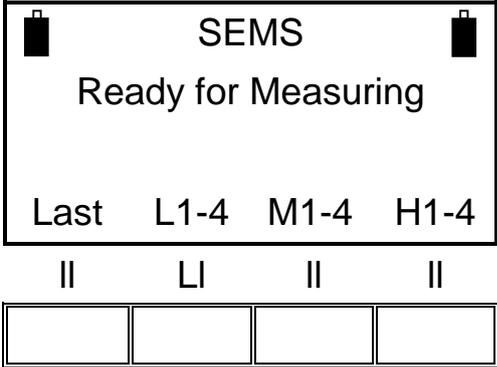
**3.1.2. Show menu**

The show menu will provide the results of measurements performed and previously stored

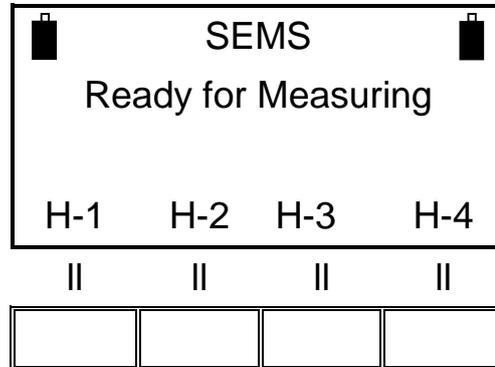
To see the saved measurements press the Show button



e.g. We will choose a measure stored in a memory named H1-4



Then we recall the H1 memory

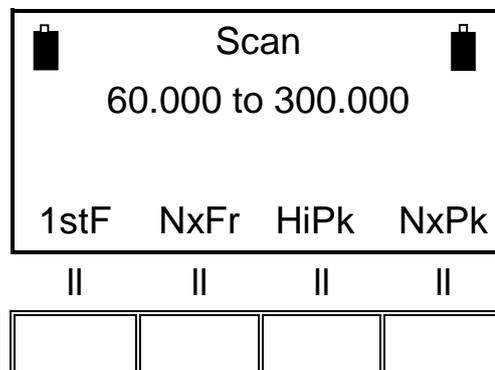


**1stF** Shows the attenuation at the lower frequency of the selected scan or list

**NxFr** Shows the attenuation on the next frequency

**HiPk** Shows the minimum attenuation on the whole scan or list

**NxPk** Shows the first relative minimum of attenuation from the current frequency



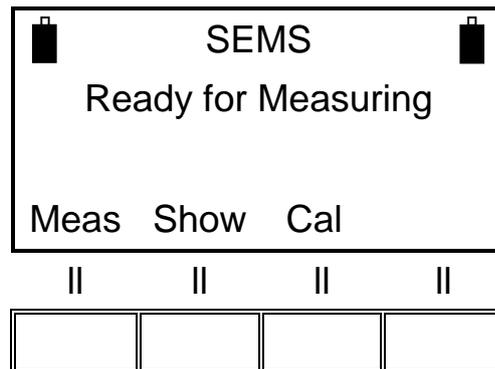
By pressing the **Last** button you will see the results of the last measurement performed, by pressing the remaining three buttons you can see the other stored data. (up to 4 for each button).

As soon as we choose the measure to see you can analyze frequency by frequency the measured attenuation. (The frequencies are always expressed in MHz)

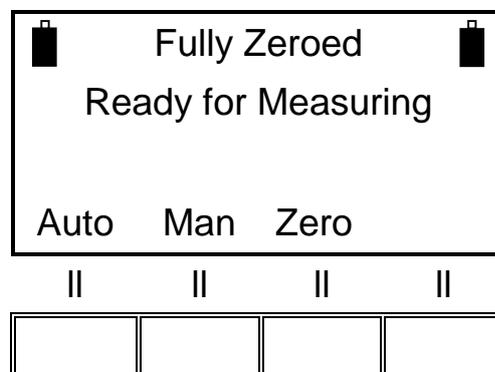
By pressing the **ESC** button you can go back to the previous menu.

### 3.1.3 Meas menu

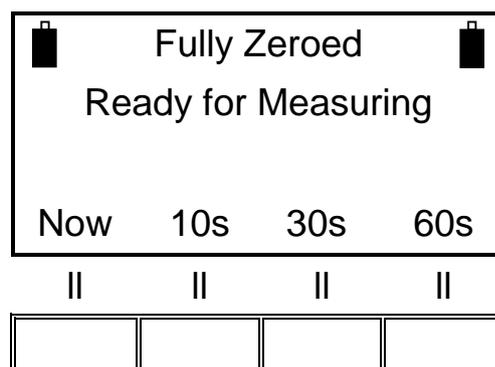
You can find the **Meas** command in the **Std** menu, but it will appear only when the system is zeroed using the **Cal** command described in the previous paragraph (3.1.1. of this manual).



The command will perform a measurement of attenuation automatically (**Auto**), or manually (**Man**).

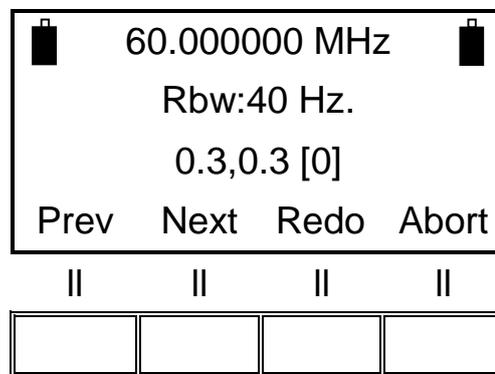


Using the automatic mode you can choose if you want the measurement procedure to start immediately (**Now**), or with a fixed time delay (**10s**, **30s**, **e 60s**).



If you use a manual measurement you will use the commands: **(Prev)** measure of the previous frequency, **(Next)** measure of the next frequency, **(Redo)** in order to measure the current frequency and **(Abort)** to end the measurement.

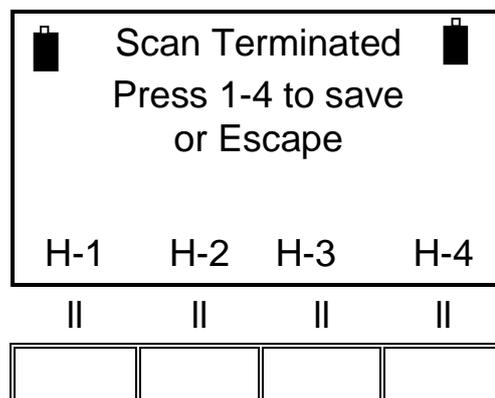
This feature can be used as a modality of RF leaks(sniffer) in order to identify weaknesses in the shielding of the room. TX unit has to be placed approximately at 1 meter from the area analyzed. To measure the electrical component we recommend to use Rod Antennas ,Mod. R-1, completely closed on the RX unit and completely open on the TX unit. For the magnetic field you can use the pairs of Loop Antennas L-1 or L-2.



When the measurement is finished the display will show the memory slot to store the acquired data, you can choose one of the 4 memories for each frequency range:

- Frequency Range from 0.01 to 2 MHz = memory (**L-1**, **L-2**, **L-3** e **L-4**)
- Frequency Range from 2 to 60 MHz = memory (**M-1**, **M-2**, **M-3** e **M-4**)
- Frequency Range from 60 to 300 MHz = memory (**H-1**, **H-2**, **H-3** e **H-4**)

Example: Save request in the memory slots from 60...300 MHz range:





USER'S MANUAL

S E M S

By pressing the H-1 button the data will be stored and you will go back to the starting screenshot.

### 3.2. WIZ menu

To improve the managing of measurement saving procedure you can use the SEMS's wizard for a better organization of data storage.

To use the wizard press the **WIZ** button in the top menu of the device. The wizard will lead the user throughout the procedure asking the following questions:

- The selection of the chamber where the measurements are performed (A, B, C, D): Using A, B, C e D you can identify a shielded chamber. Then the user has to remember the letter assigned to the chamber where the measurements were done.

|   |            |   |   |  |   |
|---|------------|---|---|--|---|
|  | Choose the |   |   |  |  |
| Chamber you want  |            |   |   |  |   |
| To measure  |            |   |   |  |   |
| A   | B          | C | D |  |   |
|   |            |   |   |  |   |
|   |            |   |   |  |   |

- The choice of the maximum number of spot to measure (1, 2, 4, 8): Represents the number of measuring spot assigned for each chamber. The user must sort chronologically the measured spot and he will find the same order in the instrument memory.

|   |                |   |   |  |   |
|---|----------------|---|---|--|---|
|  | Select the max |   |   |  |  |
| number of spot  |                |   |   |  |   |
| to be measured  |                |   |   |  |   |
| 1   | 2              | 4 | 8 |  |   |
|   |                |   |   |  |   |
|   |                |   |   |  |   |

- The selection of ranges (antennas) to measure (1, 2, 3, 4): it represents the number of antennas systems available to the user during the measurements. When you perform the measurements at all the points specified previously, the system will switch range, asking you to replace the antennas and redo the auto zero procedure.

|  |   |   |   |   |
|--|---|---|---|---|
|  |  | Select the number<br>of ranges (antennas)<br>to be measured |  |   |
|  | 1   | 2   | 4   | 8   |
|  |   |   |   |   |
|  | <input style="width: 50px; height: 20px;" type="text"/>                           | <input style="width: 50px; height: 20px;" type="text"/>     | <input style="width: 50px; height: 20px;" type="text"/>                             | <input style="width: 50px; height: 20px;" type="text"/> |

### 3.2.1. Measurement using wizard

After the selection of the chamber, spots and ranges the instrument will start the procedure to perform the auto zero required by the first set of antennas to be used.

The procedure to follow for this purpose is exactly the same of the auto zero calibration as described in chapter 3.1.1. of this manual.

|  |   |   |   |
|--|---|---|---|
|  |  | Choose the range<br>for Antenna 1<br>(Zero)             |  |
|  | Scan  | List  |   |
|  |   |   |   |
|  | <input style="width: 50px; height: 20px;" type="text"/>                             | <input style="width: 50px; height: 20px;" type="text"/> | <input style="width: 50px; height: 20px;" type="text"/>                               |

Selecting "Scan" we can choose to zeroing the system using the default mode (L\_Lo - L\_Hi - BIC) or to use the span programmable by the "SEMS PC\_Utility" software mode (User).

|  |      |     |      |
|--|------|-----|------|
|  Choose the range  |      |     |      |
| for Antenna 1  |      |     |      |
| (Zero)   |      |     |      |
| L_Lo   | L_Hi | Bic | User |
|  |      |     |      |
|  |      |     |      |

As soon as the zeroing procedure is completed, the measurement screenshot will appear on the display.

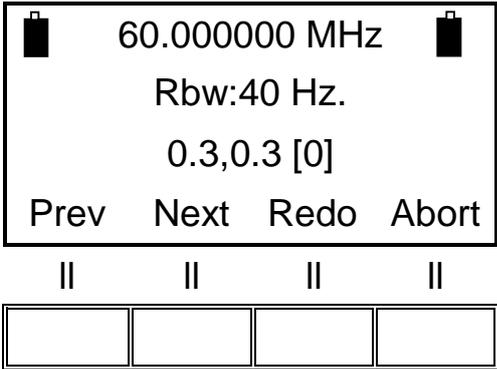
In this screenshot the user has to decide how to perform the measurements: automatically (**Auto**), or manually (**Man**).

|  |  |  |  |
|--|--|--|--|
|  Fully Zeroed  |  |  |  |
| Ready for Measuring  |  |  |  |
| Auto    Man  |  |  |  |
|  |  |  |  |
|  |  |  |  |

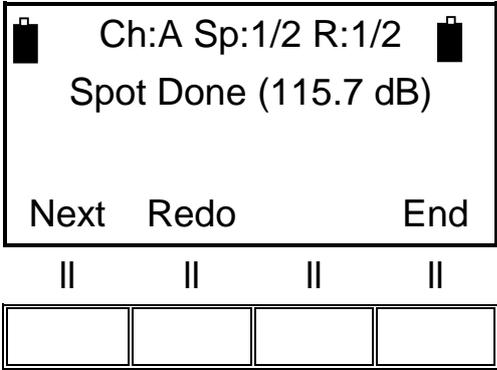
Choosing the automatic mode we can make it start immediately (**Now**), or to set a fixed time countdown before starting (**10s**, **30s**, **e 60s**).

|  |  |  |  |
|--|--|--|--|
|  Fully Zeroed  |  |  |  |
| Ready for Measuring  |  |  |  |
| Now    10s    30s    60s   |  |  |  |
|  |  |  |  |
|  |  |  |  |

When the manual mode is selected , the user has to choose the commands: **(Prev)** to measure the previous frequency, **(Next)** for the next frequency, **(Redo)** to repeat the measurement on the current frequency or **(Abort)** to quit.



After this choice the measurement will be performed, and will appear the wizard management screenshot to control the status of procedure.



In this screenshot “Ch:A” means that the chosen chamber is called “A”, “Sp:1/2” is the measurement spot index (in this case the spot is the 1st of the 2), “R:1/2” is the antennas system (range) index (in this case we are using the system 1 of 2).

“Spot Done” means that the measurement is completed for this spot with the indicated range, the value shown nearby beneath brackets is the maximum attenuation of the whole frequencies.

The **Next** button must be pressed to get to the next spot. If all the required spot have been measured, the procedure automatically switch to the next pair of antennas and shows again the auto zeroing screenshot. If you used all the

antennas systems that you selected , the procedure is over and it will return to the main screenshot with a success message about the data storing.

The **Redo** button repeats the measurement for the selected spot shown in the screen, as soon as this operation is completed the display will show the same screenshot with the updated value of the maximum attenuation.

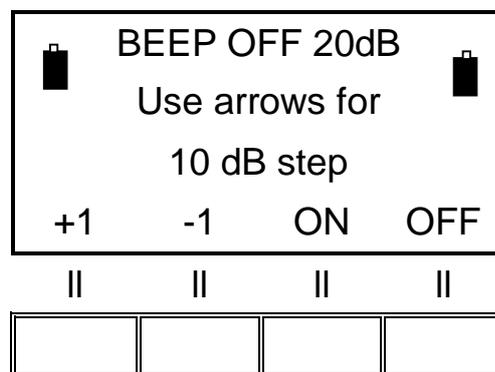
The **End** button stops the measurements with the current set of antennas. By pressing it there will be the change of the antennas and the auto zero procedure, if the antennas systems have all been selected the procedure will end with a message of success about the storing of the data and you will go back to the main screenshot.

**WARNING:** Pressing the “End” button in the first antennas system will reduce the spots for all other systems. (e.g. if I select 8 spots and I measure 3, pressing end will reduce to 3 the maximum number of spot per system. But if we perform measure on all of the 8 spots, then we will change antennas, and then again we will press the end button after just 3 spots measured and all the 5 spots will be kept.

### 3.3. STP Menu

SEMS has an internal buzzer that beeps when a customizable alarm threshold is exceeded.

To activate this function is necessary to press the “Stp” button in the main screenshot shown as you turn the instrument off.



Using the up and down arrows on the SEMS keyboard is possible to move the threshold by 10 dB, to set a more fine value is possible to press the **+1** and **-1** buttons to increase or decrease the threshold by 1 dB.

By pressing the **ON** button the buzzer will be activated, and during the measurements if the attenuation measured drops below the threshold the buzzer will produce an acoustic signal.

While the measured value remains under the threshold the buzzer will produce a fast series of beeps, when the measured value returns over the threshold the buzzer will be still beeping but with a slower series of sounds. The **OFF** button will take the sound off.

The sound mode status is reported on the top of display in this menu “BEEP ON” and “BEEP OFF”.

The actual threshold is written on the right top of screen (in this example is 20 dB)

### 3.4. Measuring the shielding attenuation

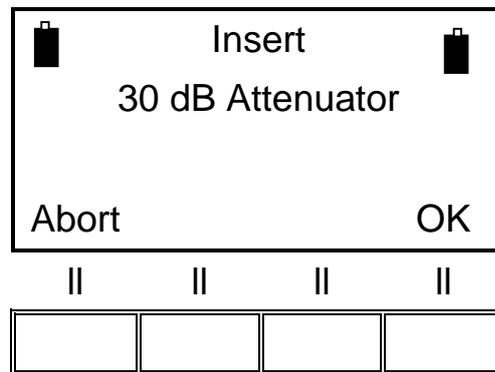
- 1) Place the receiver and the transmitter on the 120 cm height non conductive tripods, and place them 40/60 cm if you are using the loop antennas and 100/200 cm if you are using biconical ones.
- 2) Connect the antennas upon the transmitter and receiver being careful to align them in a parallel way.
- 3) Connect the wireless transducers to the RS232 port on the transmitter and the receiver, turn on both devices and wait until the green blinking light stops and remain turned on and the two icons of the batteries become visible on the receiver's display. Is recommended to wait a few minutes before going on (warm-up).
- 4) Perform the zeroing procedure by using the **Cal** button, select then **Scan** or **List** for the desired frequencies.
- 5) As soon as the zeroing procedure is over move the receiver into the shielded environment near the first measurement point and the transmitter outside trying to maintain the same distance used during the zeroing plus the shield width.
- 6) Measure the attenuation pressing the **Meas**, **Auto** and **10s** button to allow the user to move away from the measuring system.
- 7) As the measure ends save the result in a memory.
- 8) Repeat the 5, 6 and 7 steps for each measurement spot.
- 9) After all the spots are measured download the results on a PC using SEMS PC Utility software provided with the product.

### 3.5. Calibration using Calkit

The SEMS needs a periodic linearity calibration, the Cal-Kit can easily and precisely accomplish this purpose. If required the Cal-Kit can be provided with SIT calibration.

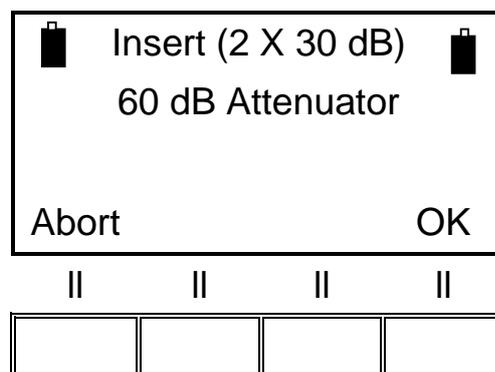
To start the calibration procedure press **Cal** button from the main menu and press **CalK** button, then calibration can be performed following the instructions on display.

This screenshot shows the request for the 30 dB attenuator



Connect the Tx and Rx using the 30 dB attenuator and press the OK button

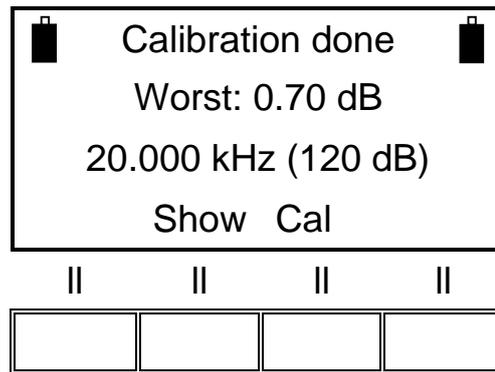
This screenshot shows the request for the second attenuator



Connect the second attenuator and then press the OK button

Repeat the same operation until you will have used all the four 30 dB attenuators (4x30 dB= 120 dB)

When calibration is finished the following screenshot will be shown



The “Worst” parameter shows the worst accuracy over frequencies (in this case is 0.7 dB at 20.000KHz) typically is a parameter that you can find in the technical specifications of the chamber:

10 kHz... 30MHz  $\pm$  1.0dB  
 30 MHz...300MHz  $\pm$  1.5dB

The following images show the procedure set-up.



Picture n°07



Picture n°08

### 3.6. How to use the active bridge

The active bridge is developed to improve the connection between Tx and Rx, this is very useful when the shielding that is tested is too high to ensure the direct wireless connection between the devices (2.4GHz), using the wireless/optical cable adapter you can solve the problem allowing the regular performing of the test.

The active bridge consists in two wireless/optical fiber adapter modules called "wireless bridge master" and "wireless bridge slave", the modules are connected by the optical cable, and is powered by (Ni-Mh AAA) rechargeable batteries (the battery charger is included).

To set up the active bridge is necessary to turn on the wireless bridge master device and the module linked to the RS232/wireless adapter called "slave" and waiting for their connection.

The next step is to turn on the wireless bridge slave device and the other module and waiting for their connection.

In both cases the successful connection will be confirmed by the green light led steadily on both the modules.

As soon as the connection is established it's possible to check the battery status of the Tx on the Rx display.

The optical fiber which connects the master and slave devices should pass under the door in a fingerless zone, if the finger do not allow the fiber placement the proper channel located typically near the filter's panel should be used.

**IMPORTANT NOTE:** As soon as the connection is established, if the red led of the wireless devices blink together with the yellow ones, wait until the complete switching off of the first ones in order to let the devices synchronize and ensure the correct functioning.

On the active bridge devices there is no red led, just wait for the complete switching off of the red led on the TX/RX to ensure the proper functioning.

### 3.7. Measurement with Rod antennas mod. R1

When using Rod antennas( in the zero setting and in the measurement phase) it's absolutely necessary to connect the SEMS TX 10 dB attenuator ,already supplied, before connecting the Rod antenna (image n.09)

**WARNING:** not using the attenuator can cause serious troubles to the system functionality.



Picture n°09

## 4. SEMS PC Utility software, controls and functions

### 4.1. Installation

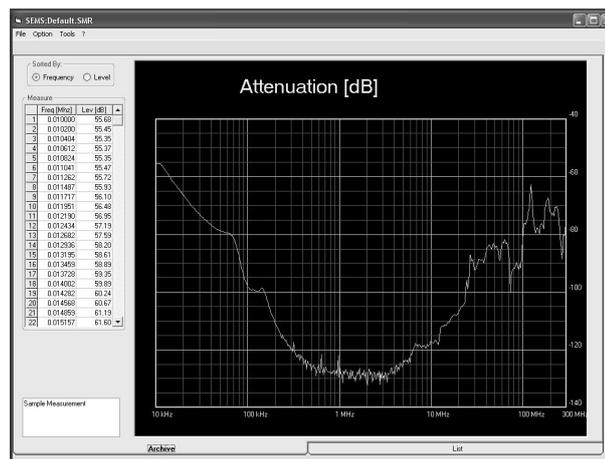
Launch the Setup file located in the USB pen drive provided with the product and follow the instructions.



After the installation the software is ready to use

### Options menu

SEMS PC Utility starts from the desktop icon or from **start / Programs**.



The program has two working modes: **Archive** shown at the program start up and **List**, in archive mode is possible to load files and show measurements, in the list mode is possible to create and send to the receiver the list of frequencies for customized measurements.

## 4.2. Archive mode

Menu:

### **File**

|               |   |
|---------------|---|
| <i>Save</i>   | Saves the files in the chosen directories                   |
| <i>Load</i>   | Loads the files from the chosen directories                 |
| <i>Export</i> | Exports data in file.xls with two available data separators |
| <i>Exit</i>   | Quits the program   |

### **Option**

|                             |  |
|-----------------------------|--|
| <i>Select Comm</i>          | Selection of the com serial port                             |
| <i>Graphic colors</i>       | Changes the graphic colors                                   |
| <i>Diagram style</i>        | Selection of two ways in order to represent the data diagram |
| <i>Default Graphic Axis</i> | Restore the default graphic visualization                    |

### **Tools**

#### *Retrieve*

*Single measure: Retrieve the stored measurements made in standard mode (Std) from the receiver using RS232 connection*

*Set of measure: Retrieve the stored measurements made by the wizard (Wiz) using RS232 connection*

*Get CalK Report: Produces a text file containing the last calibration data performed using the CalK procedure. (You can find CalK\_Report.TXT file in the folder where you installed SEMS PC Utility Software)*

*Update Firmware* Updates the receiver's firmware

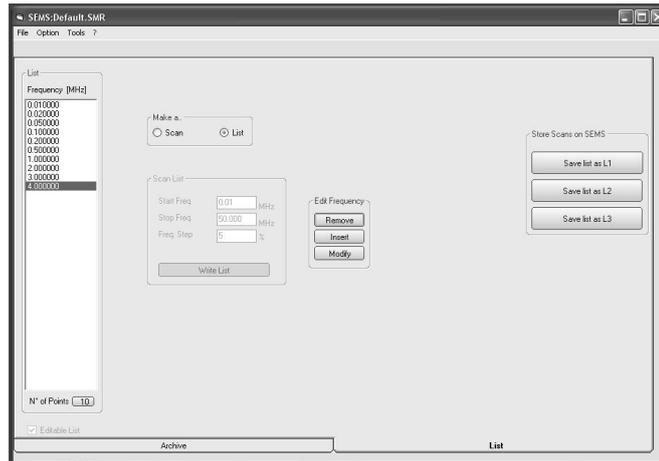
In the Archive mode you can see on the left side of the window the numerical results that can be sorted by frequency or dB level, in the box below is possible to add a comment when saving the data.

You can change the scale by double clicking on the maximum and minimum value in the graphic.

(\*) In addition to RS232 connection, you can connect the SEMS receiver to the PC using the wireless device, the connection takes place between the SEMS receiver wireless and the PC wireless.

### 4.3. List mode

Clicking on the **List** button, on the right bottom of the window, the second working mode will be activated.

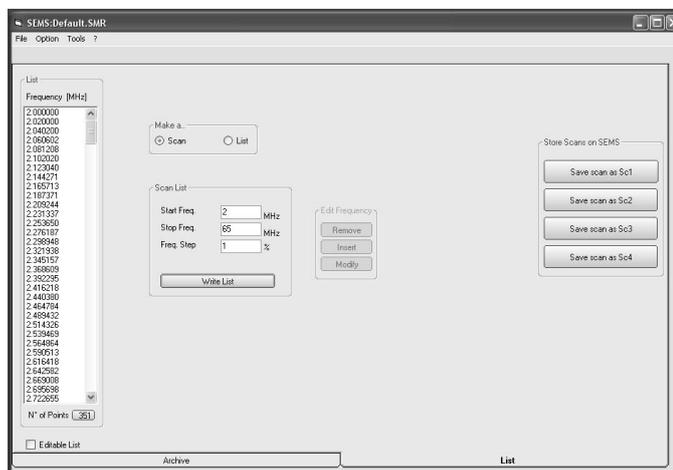


Here you can find how to create a frequency list to upload in the SEMS as customized frequencies:

For an automatic table creation press the **Scan** button after **Start Freq.**, **Stop Freq.** and **Freq. Step** are selected or **Write List** or **List** to insert manually any kind of frequency. The maximum number of frequencies allowed for each scan or list is 640.

In order to edit a scan you need to activate the **Editable List** flag.

As the table creation is completed is possible to save on PC pressing the **Save** button or uploading it to the receiver choosing one of the four available memories in scan or three available memories in list.



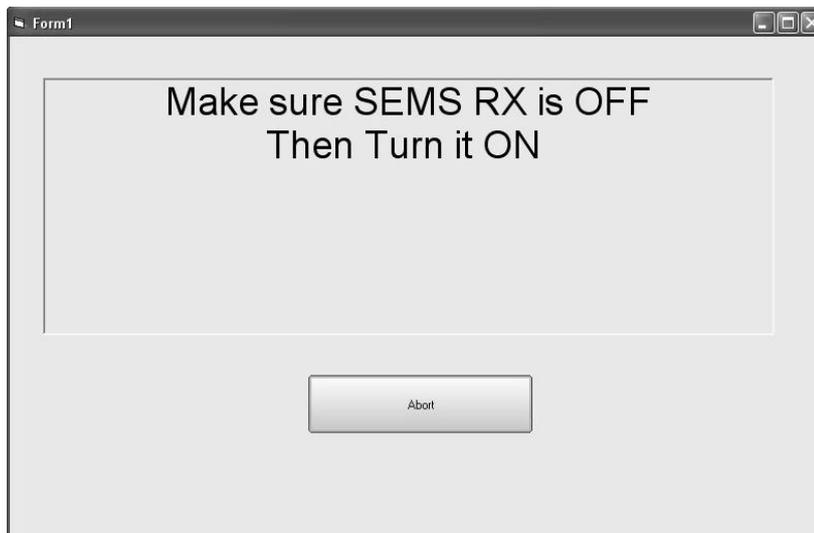
#### 4.4. Receiver firmware upgrade

Recharge the receiver batteries and connect it to the PC using RS232 cable. Turn on the Rx, run the SEMSPC\_Utility software and set the COM port in the Option menu pressing Select Comm.

*To verify the assignation of the COM port assigned by the PC check in the control panel, System, Hardware, peripheral, ports.*

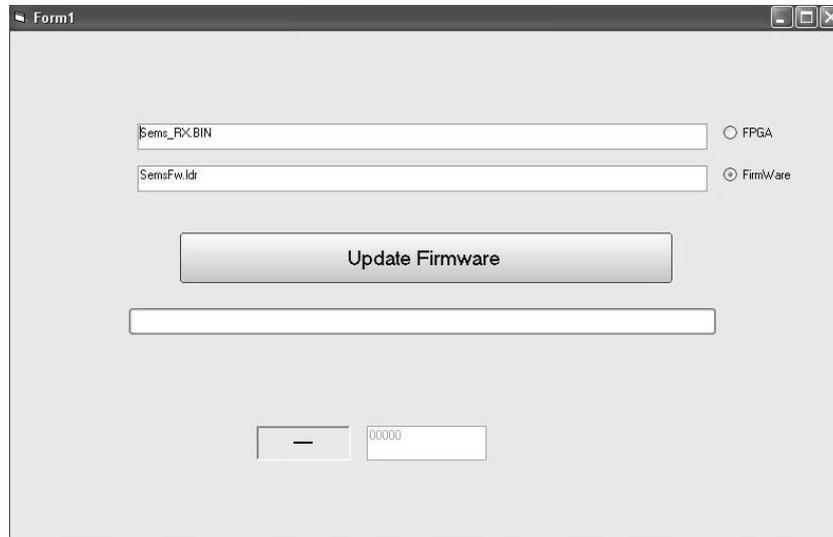
To start the firmware update procedure, click the "Tools" button , Update Firmware, Update Rx.

The following screenshot will appear:



Turn off the receiver and then turn it on again.

It will show the upgrade window:



The updatable file (SemsFw.ldr) should be located in the SEMS software directory. Press the “Update Firmware” button and wait for the loading. When the upgrade is complete, close the “Form1” window and turn off the receiver.

Other information: [www.gruppompb.com](http://www.gruppompb.com)

Technical information: [assistenza@gruppompb.com](mailto:assistenza@gruppompb.com)

Phone +39 06 41200744